

and mobility

Marie Curie Actions

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We assume that in indentation testing, an articular cartilage sample may be modeled as a viscoelastic layer of finite thickness bonded to a rigid substrate. Following Brown *et al.* (2009), we consider the so-called rebound indentation test, which is composed of two stages. In the first stage, called the indentation phase, the sample is subject to loading at a constant speed  $v_0$  to  $n_1$  per cent strain. That is the indenter displacement is assumed to be specified according to the law

$$w^{(1)}(t) = v_0 t, \quad 0 \le t < t_1.$$
 (1)

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Further, we assume that at  $n_1$  per cent strain the load is immediately removed and the second stage, called the recovery phase, lasts for a theoretically indefinite time. In the recovery phase, we have

$$P^{(2)}(t) = 0, \quad t \ge t_1.$$
 (2)

We underline that in the first stage, the function  $w^{(1)}(t)$  is specified by Eq.(1), while  $P^{(1)}(t)$  is unknown. In the second stage, on the contrary, the displacement function  $w^{(2)}(t)$  is unknown, whereas the contact loading  $P^{(2)}(t)$  is specified by Eq.(2).